

Department of Leather Engineering
Khulna University of Engineering & Technology
 B. Sc. Engineering 1st Year 1st Term Examination-2021
Basic Electrical Engineering
EEE 1119

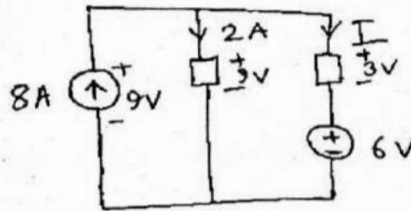
Time: 3.0 Hours

Full Marks: 210

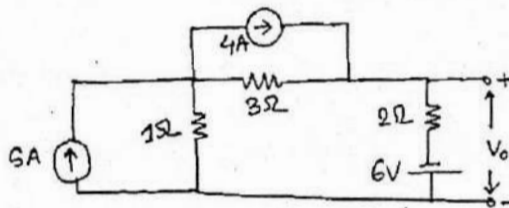
- N.B. i) Answer any three questions from each section in separate scripts.
 ii) Figures in the right margin indicate full marks.
 iii) Assume reasonable data if any missing.

SECTION-A

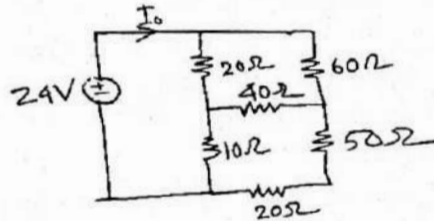
- 1(a) Write short notes on the following: (i) KVL (ii) KCL and (iii) Ohm's Law and (iv) Circuit parameters 12
- 1(b) Find I and the power absorbed by each element in the circuit of the following figure. 10



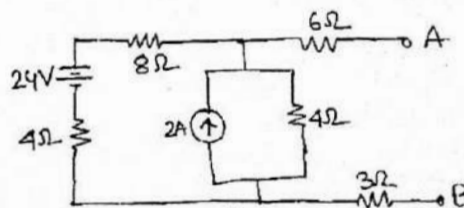
- 1(c) State the conditions for applying superposition theorem to a circuit. Using super position theorem, find the value of the output voltage V_0 in the circuit of the following figure. 13



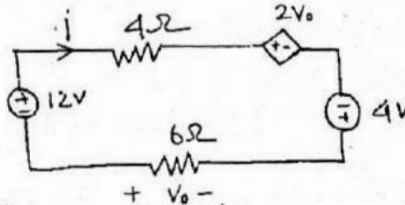
- 2(a) Deduce the equations for Delta to wye (Δ -Y) conversion. Calculate the current I_0 in the circuit of the figure. 14



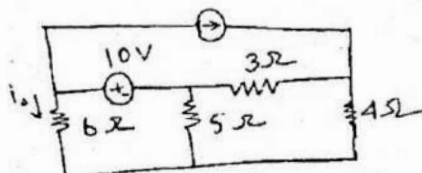
- 2(b) State Thevenin's theorem. By using this theorem, replace the network shown in figure with reference to terminals A and B. 12



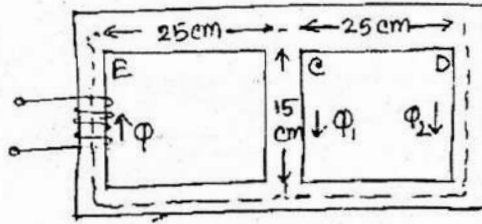
- 2(c) Determine V_0 and I in the circuit of the figure. 09



- 3(a) Explain nodal analysis. Apply nodal analysis to find i_0 and the power dissipated in each resistor in the circuit of the figure. 14



- 3(b) What do you mean by 1 Tesla? A cast steel magnetic structure made for a section $8\text{ cm} \times 2\text{ cm}$ is shown in the figure. Determine the current that the 500 turn-magnetizing coils on the left limb should carry so that a flux of 2 mwb is produced in the right limb. Take $\mu_r = 600$ and neglect leakage. 14



- 3(c) Transform these sinusoids to phasors; and estimate the sinusoid of power (p). 07
 $i = 6\cos(50t - 40^\circ)$; $v = -4\sin(30t + 50^\circ)$
- 4(a) Define impedance. Derive the equation for impedance and power for R-L and R-C branch. Show graphical representation of voltage, current and power variation in these branches. 15
- 4(b) Find all possible roots of $\sqrt[3]{\frac{10\angle 45^\circ 5e^{-j60^\circ} (-4.047 - j2.94)}{1 - j1.732}}$ 10
- 4(c) What is the phase relationship between the sinusoidal waves of each of the following: 10
 (i) $v = -10\sin(\omega t + 30)$; $i = 5\sin(\omega t + 10)$ (ii) $i = 2\cos(\omega t + 60)$; $v = -3\sin(\omega t - 150)$

SECTION-B

- 5(a) Explain the basic components of a DC machine. Also, describe the function of brush and Commutator. 13
- 5(b) Classify and draw different types of DC generator according to their field and armature coil arrangement. 15
- 5(c) Explain back e.m.f with the significance. 07
- 6(a) Describe the Mechanisms of dc motor. Speed control with corresponding circuit and equation. 10
- 6(b) Describe the operating principle of a 3ϕ induction motor. The power input to the rotor of a 400V, 50Hz, 6-pole, 3-phase induction motor is 20KW. The slip is 3%. Calculate: 15
 (i) The frequency of the rotor current (ii) rotor speed (iii) rotor copper loss and (iv) rotor resistance per phase if rotor current is 80A.
- 6(c) What is a slip? Draw the (i) equivalent circuit and (ii) Torque-speed characteristics of an induction motor. 10
- 7(a) What are the losses in a transformer? Define efficiency and find the condition for maximum efficiency of a transformer. 10
- 7(b) Describe the voltage transformation ratio for step-down and step-up transformers. The maximum flux density in the core of a 250/3000-volts, 50-Hz single-phase transformer is 1.2 wb/m^2 . If the emf per turn is 8V determine: (i) Primary and secondary turns (ii) Area of the core 15
- 7(c) Draw the circuit for open-circuit test and short circuit test of a transformer. What are the functions of these test? 10
- 8(a) Explain the basic principle of 3ϕ synchronous generator. Also write five basic differences between synchronous generator and DC generator. 10
- 8(b) What are the basic differences between synchronous motor and induction motor? 05
- 8(c) Why synchronous motor is not self-starting? 10
- 8(d) Explain working Principle and applications of servo-motor. 10